

# MSICT

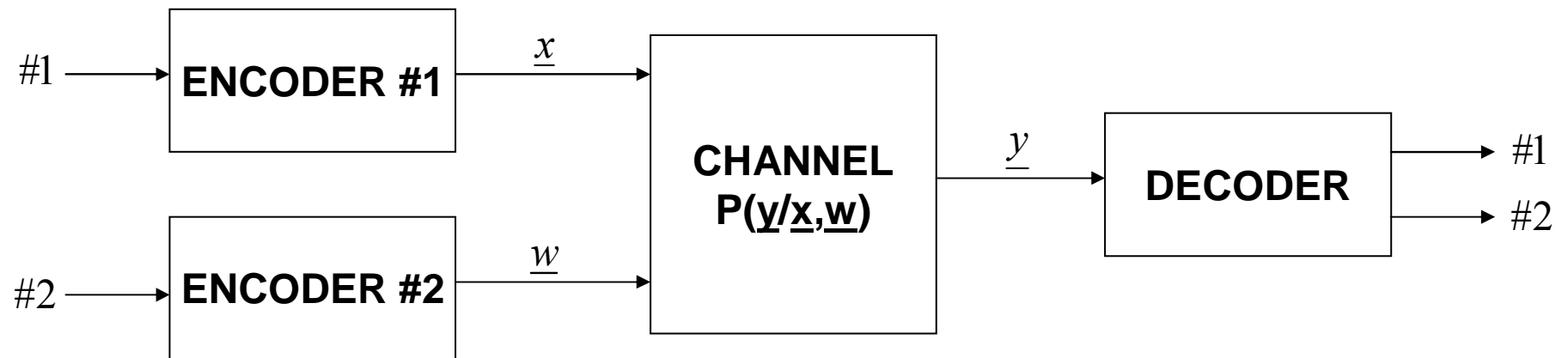
**Master of Science in Information and Communication  
Technologies**

**COMMUNICATION THEORY**

***MULTIPLE ACCESS***

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## MULTIPLE-ACCESS CHANNELS



Alphabets:  $A_x, A_w, A_y$

$$\begin{array}{l} \underline{x} = (x_1, x_2, \dots, x_N) \\ \underline{w} = (w_1, w_2, \dots, w_N) \end{array} \left| \begin{array}{l} \longrightarrow \\ \longrightarrow \end{array} \right. \text{Block coding} \longrightarrow \begin{cases} \{\underline{x}_1, \underline{x}_2, \dots, \underline{x}_M\} & M \\ \{\underline{w}_1, \underline{w}_2, \dots, \underline{w}_L\} & L \end{cases}$$

For a *DMC*, we have that:

$$P(\underline{y} / \underline{x}, \underline{w}) = \prod_{n=1}^N P(y_n / x_n, w_n)$$

and the rates for the two sources are given by:

$$R_1 = \frac{\ln M}{N} \quad R_2 = \frac{\ln L}{N}$$

From Ahlswede-Liao:

$$\begin{aligned} R_1 + R_2 &\leq I(x, w; y) \\ 0 &\leq R_1 \leq I(x; y / w) \\ 0 &\leq R_2 \leq I(w; y / x) \end{aligned}$$

From the definition of mutual (*average*) information:

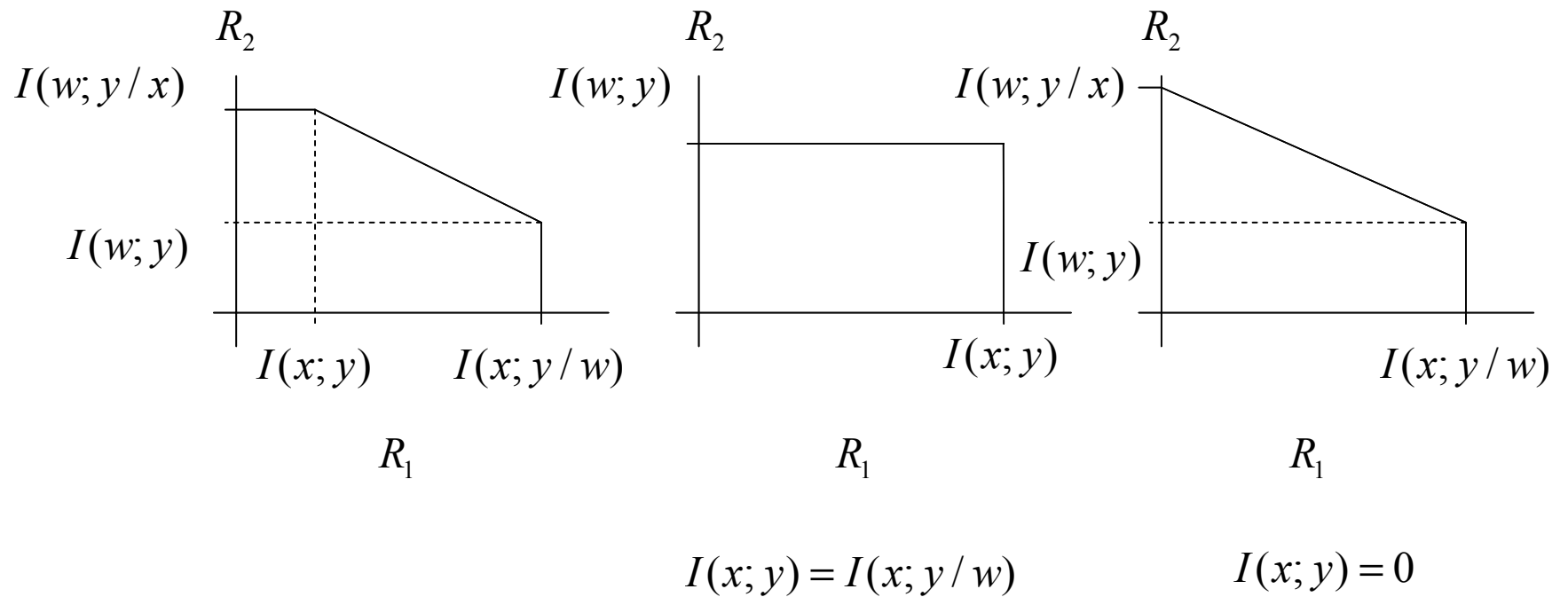
$$I(A^x; A^y) \equiv E[I(x; y)] = \sum_x \sum_y P(x; y) \ln \frac{P(y/x)}{P(y)}$$

we have that:

$$\begin{aligned} I(x, w; y) &\equiv \sum_x \sum_w \sum_y P(x, w; y) \ln \frac{P(y/x, w)}{P(y)} = \\ &= \sum_x \sum_w \sum_y P(y/x, w) P_1(x) P_2(w) \ln \frac{P(y/x, w)}{P(y)} \end{aligned}$$

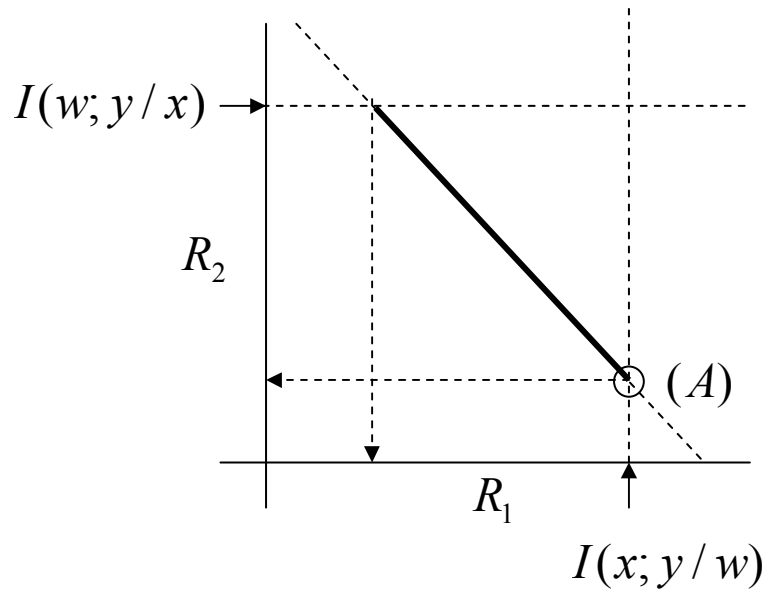
$$I(x; y/w) \equiv \sum_x \sum_w \sum_y P(y/x, w) P_1(x) P_2(w) \ln \frac{P(y/x, w)}{P(y/w)}$$

$$I(w; y/x) \equiv \sum_x \sum_w \sum_y P(y/x, w) P_1(x) P_2(w) \ln \frac{P(y/x, w)}{P(y/x)}$$



**Notice that for x & w independent:**

$$I(x; y/w) \geq I(x; y) \quad ; \quad I(w; y/x) \geq I(w; y)$$



In (A):  $R_1 = I(x; y/w)$

We know that in (A)

$$R_1 + R_2 = I(x, w; y)$$

and thus:

$$I(x; y/w) + R_2 = I(x, w; y)$$

or:

$$R_2 = I(x, w; y) - I(x; y/w)$$

$$\begin{aligned} R_2 &= \sum_{xyw} P(x, w, y) \ln \frac{P(y/x, w)}{P(y)} - \sum_{xwy} P(x, w, y) \ln \frac{P(y/x, w)}{P(y/w)} = \\ &= \sum_{xwy} P(x, w, y) \ln \frac{P(y/w)}{P(y)} = I(w; y) \end{aligned}$$

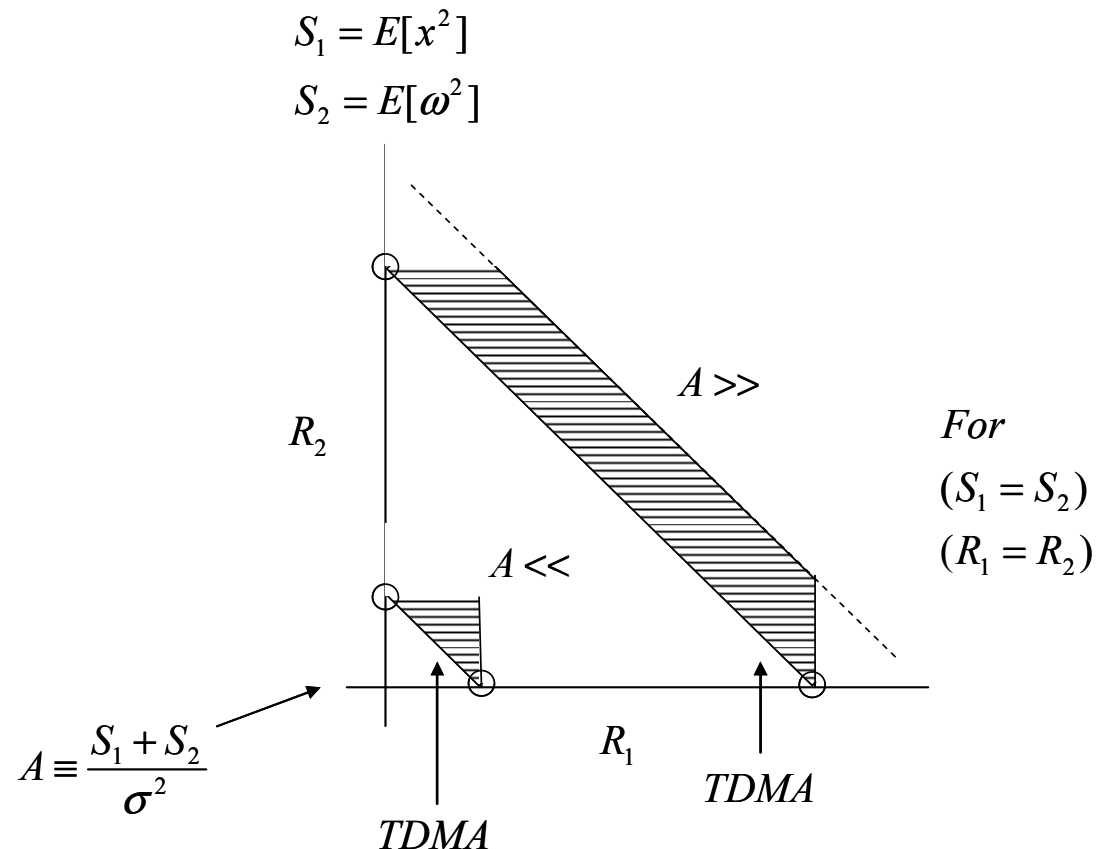
For the AWGN channel:

$$y = x + w + \underset{\substack{\downarrow \\ \text{Noise}}}{z} \quad z \sim N(0, \sigma^2)$$

$$I(x, w; y) \leq \frac{1}{2} \log \left( 1 + \frac{S_1 + S_2}{\sigma^2} \right)$$

$$I(x; y/w) \leq \frac{1}{2} \log \left( 1 + \frac{S_1}{\sigma^2} \right)$$

$$I(w; y/x) \leq \frac{1}{2} \log \left( 1 + \frac{S_2}{\sigma^2} \right)$$



Consider the following multiple access scheme:

$$\underline{y} = \sum_{i=1}^K \sqrt{p_i} x_i \underline{\phi}_i + \underline{w}$$

The linear detector for user#1 will be given by:

$$\hat{x}_1 = \underline{\phi}_1^H \underline{y} = \underbrace{\sqrt{p_1} x_1 \underline{\phi}_1^H \underline{\phi}_1}_{\text{User \#1}} + \underbrace{\sum_{i=2}^K \sqrt{p_i} x_i \underline{\phi}_1^H \underline{\phi}_i}_{\text{Multiple-access Interference (MAI)}} + \underbrace{\underline{\phi}_1^H \underline{w}}_{\text{Noise}}$$

Depending on the signature set,  $\{\underline{\phi}_i\}_{1 \leq i \leq K}$  the ‘*Multiple Access Interference*’ (MAI) can be a significant impairment for achieving a reliable communication.

We can try to optimize the linear detector.

We now consider the more *general linear scheme*:

$$\hat{x}_1 = \underline{\omega}_1^H \underline{y} = \sqrt{p_1} x_1 \underline{\omega}_1^H \underline{\phi}_1 + \sum_{i=2}^K \sqrt{p_i} x_i \underline{\omega}_1^H \underline{\phi}_i + \underline{\omega}_1^H \underline{w}$$

such that:

$$\max_{\underline{\omega}_1} SINR \equiv \frac{p_1 E[|x_1|^2] |\underline{\omega}_1^H \underline{\phi}_1|^2}{\sum_{i=2}^K p_i E[|x_i|^2] |\underline{\omega}_1^H \underline{\phi}_i|^2 + E|\underline{\omega}_1^H \underline{w}|^2}$$

or:

$$\min_{\underline{\omega}_1} E[|x_1 - \hat{x}_1|^2] = E[|x_1 - \underline{\omega}_1^H \underline{y}|^2]$$

We can also write the signal model as follows:

$$\underline{y} = \sqrt{p_1} x_1 \underline{\phi}_1 + \underline{z}$$

Where:

$$\underline{z} \equiv \sum_{i=2}^K \sqrt{p_i} x_i \underline{\phi}_i + \underline{w} \quad (\equiv MAI + Noise)$$

In general,  $\underline{z}$  is NOT considered white because of the MAI, but we can simplify the problem considering that  $\underline{z}$  is white. Under this assumption:

$$\hat{x}_1 = \frac{1}{\underline{\phi}_1^H \underline{\phi}_1} \underline{\phi}_1^H \underline{y} \quad (\text{conventional matched-filter})$$

that is, the MAP/ML optimal detector corresponds to the projection of the observation on the desired user signature.

We see that  $\underline{z}$  is not white:

$$\underline{z} \equiv \sum_{i=2}^K \sqrt{p_i} x_i \underline{\phi}_i + \underline{w} \equiv \underline{\Phi}_{\underline{1}} \underline{P}_{\underline{1}}^{1/2} \underline{x}_1 + \underline{w}$$

where:

$$\underline{\Phi}_{\underline{1}} \equiv \begin{bmatrix} \underline{\phi}_2 & \underline{\phi}_3 & \dots & \underline{\phi}_K \end{bmatrix}$$

$$\underline{P}_{\underline{1}}^{1/2} \equiv \text{diag} \left[ \sqrt{p_2} \quad \sqrt{p_3} \quad \dots \quad \sqrt{p_K} \right]$$

$$\underline{x}_1 \equiv [x_2, x_3, \dots, x_K]^T$$

and:

$$\underline{\Sigma} \equiv E[\underline{z}\underline{z}^H] = \underline{\Phi}_{\underline{1}} \underline{P}_{\underline{1}}^{1/2} \overbrace{E[\underline{x}_1 \underline{x}_1^H]}^{\underline{I}} \underline{P}_{\underline{1}}^{1/2} \underline{\Phi}_{\underline{1}}^H + E[\underline{w}\underline{w}^H] = \underline{\Phi}_{\underline{1}} \underline{P}_{\underline{1}} \underline{\Phi}_{\underline{1}}^H + \sigma^2 \underline{I}$$

The eigendecomposition of  $\Sigma$  is given as usual:

$$\underline{\underline{\Sigma}} = \underline{\underline{Q}} \underline{\underline{\Lambda}} \underline{\underline{Q}}^H$$

Thus, if we now take the following projection of the *MAI+Noise* term:

$$\underline{\underline{\tilde{z}}} \equiv \underline{\underline{\Lambda}}^{-1/2} \underline{\underline{Q}}^H \underline{\underline{z}} \Rightarrow E[\underline{\underline{\tilde{z}}} \underline{\underline{\tilde{z}}}^H] = \underline{\underline{\Lambda}}^{-1/2} \underline{\underline{Q}}^H E[\underline{\underline{z}} \underline{\underline{z}}^H] \underline{\underline{Q}} \underline{\underline{\Lambda}}^{-1/2} = \underline{\underline{\Lambda}}^{-1/2} \underline{\underline{Q}}^H \underline{\underline{\Sigma}} \underline{\underline{Q}} \underline{\underline{\Lambda}}^{-1/2} = \underline{\underline{I}} !!$$

$\underline{\underline{\tilde{z}}}$  becomes white !!

In other words, we can think on the equivalent signal model:

$$\underline{\underline{\tilde{y}}} = \underline{\underline{\Lambda}}^{-1/2} \underline{\underline{Q}}^H \underline{\underline{y}} = \sqrt{p_1} x_1 \underline{\underline{\Lambda}}^{-1/2} \underline{\underline{Q}}^H \underline{\underline{\phi}}_1 + \underline{\underline{\tilde{z}}}$$

White term!!

Sufficient statistic

Because the whiteness of  $\underline{\tilde{z}}$ , the optimal detector is now simpler:

$$\hat{x}_1 = \lambda^* \phi_{-1}^H \underline{\underline{Q}} \underline{\underline{\Lambda}}^{-1/2} \underline{\tilde{y}} = \lambda^* \phi_{-1}^H \underbrace{\underline{\underline{Q}} \underline{\underline{\Lambda}}^{-1/2} \underline{\underline{\Lambda}}^{-1/2} \underline{\underline{Q}}^H}_{\underline{\underline{\Sigma}}^{-1}} \underline{y} = \lambda^* \phi_{-1}^H \underline{\underline{\Sigma}}^{-1} \underline{y}$$

that is:

$$\hat{x}_1 = \lambda^* \left[ \phi_{-1}^H \underline{\underline{\Sigma}}^{-1} \phi_{-1} \sqrt{p_1} x_1 + \phi_{-1}^H \underline{\underline{\Sigma}}^{-1} \underline{z} \right] \equiv \lambda^* \nu$$

with 'λ' such that:

$$\min_{\lambda} E \left[ |x_1 - \hat{x}_1|^2 \right] = E \left[ |x_1 - \lambda^* \nu|^2 \right] \equiv E \left[ (x_1 - \lambda^* \nu)^* \nu \right] = 0$$

or:

$$\lambda = \frac{E \left[ x_1^* \nu \right]}{E \left[ |\nu|^2 \right]}$$

One can see that:

$$1.- E[x_1^* v] = \sqrt{p_1} \phi_{-1}^H \Sigma^{-1} \phi_{-1} E[|x_1|^2]$$

$$2.- E[|v|^2] = p_1 (\phi_{-1}^H \Sigma^{-1} \phi_{-1})^2 + \phi_{-1}^H \Sigma^{-1} \phi_{-1}$$

or:

$$\lambda = \frac{\sqrt{p_1} (\phi_{-1}^H \Sigma^{-1} \phi_{-1})}{p_1 (\phi_{-1}^H \Sigma^{-1} \phi_{-1})^2 + (\phi_{-1}^H \Sigma^{-1} \phi_{-1})} = \frac{\sqrt{p_1}}{1 + p_1 \phi_{-1}^H \Sigma^{-1} \phi_{-1}}$$

that is:

$$\hat{x}_1^{MMSE} = \frac{\sqrt{p_1}}{1 + p_1 \phi_{-1}^H \Sigma^{-1} \phi_{-1}} \phi_{-1}^H \Sigma^{-1} y$$

$$\Sigma = \phi_{-1}^H P_{-1} \phi_{-1} + \sigma^2 I$$

We also see that:

$$\begin{aligned}
 E\left[|x_1 - \hat{x}_1|^2\right] &= E\left[|x_1|^2\right] - E\left[x_1^* \hat{x}_1\right] - E\left[\hat{x}_1^* x_1\right] + E\left[|\hat{x}_1|^2\right] = \swarrow \hat{x}_1 = \lambda^* v \\
 &= E\left[|x_1|^2\right] - \lambda^* E\left[x_1^* v\right] - \lambda E\left[v^* x_1\right] + |\lambda|^2 E\left[|v|^2\right] \geq \\
 &\geq E\left[|x_1|^2\right] - \frac{\left|E\left[x_1^* v\right]\right|^2}{E\left[|v|^2\right]} = E\left[|x_1|^2\right] - \frac{p_1 (\phi_{-1}^H \Sigma_{-1}^{-1} \phi_{-1})^2}{p_1 (\phi_{-1}^H \Sigma_{-1}^{-1} \phi_{-1})^2 + \phi_{-1}^H \Sigma_{-1}^{-1} \phi_{-1}} = 1 - \frac{p_1 \phi_{-1}^H \Sigma_{-1}^{-1} \phi_{-1}}{1 + p_1 \phi_{-1}^H \Sigma_{-1}^{-1} \phi_{-1}} \\
 \lambda_{opt} &= \frac{E\left[x_1^* v\right]}{E\left[|v|^2\right]}
 \end{aligned}$$

or:

$$\min E\left[|x_1 - \hat{x}_1|^2\right] = 1 - \frac{1}{1 + \frac{1}{SINR}} = \frac{1}{1 + SINR}$$

**We can conclude that:**

$$1.- \min E \left[ |x_1 - \hat{x}_1|^2 \right] \equiv \max \text{SINR} = \frac{S}{MAI + N}$$

2.- The maximum SINR is given by :

$$\boxed{\max(\text{SINR}) = p_1 \underline{\phi}_1^H \underline{\Sigma}^{-1} \underline{\phi}_1}$$

$$\text{for: } \underline{\Sigma} = E \left[ \underline{z} \underline{z}^H \right] = \underline{S} \underline{P} \underline{S}^H + \sigma^2 \underline{I}$$

(other formulations .../...)

The common formulation becomes:

$$\min_{\underline{\omega}} E \left[ |x_1 - \hat{x}_1|^2 \right] = E \left[ |x_1 - \underline{\omega}_1^H \underline{y}|^2 \right] \equiv E \left[ (x_1 - \underline{\omega}_1^H \underline{y})^* \underline{y} \right] = \underline{0}$$

or:

$$E \left[ x_1^* \underline{y} \right] = E \left[ \underline{y} \underline{y}^H \right] \underline{\omega}_1$$

where:

- 1.-  $E \left[ x_1^* \underline{y} \right] = \sqrt{p_1} \underline{\phi}_1$
- 2.-  $E \left[ \underline{y} \underline{y}^H \right] = p_1 \underline{\phi}_1 \underline{\phi}_1^H + \underline{\Sigma}$

and we can make use of the '*Matrix Inversion Lemma*':

$$(\underline{\underline{A}} + \underline{\underline{U}} \underline{\underline{B}} \underline{\underline{V}})^{-1} = \underline{\underline{A}}^{-1} - \underline{\underline{A}}^{-1} \underline{\underline{U}} (\underline{\underline{B}}^{-1} + \underline{\underline{V}} \underline{\underline{A}}^{-1} \underline{\underline{U}})^{-1} \underline{\underline{V}} \underline{\underline{A}}^{-1}$$

for  $\underline{\underline{A}}, \underline{\underline{B}}$  non-singular

It is also interesting to see that the direct optimization of the *SINR* leads to the same result:

$$SINR = \frac{S}{MAI + N} = \frac{p_1 \left| \underline{\omega}_1^H \underline{\phi}_1 \right|^2}{E \left[ \left| \underline{\omega}_1^H \underline{z} \right|^2 \right]} = p_1 \frac{\underline{\omega}_1^H \underline{\phi}_1 \underline{\phi}_1^H \underline{\omega}_1}{\underline{\omega}_1^H \underline{\Sigma} \underline{\omega}_1} \quad (\text{Rayleigh's quotient})$$

$$\max \frac{\underline{\omega}_1^H \underline{\phi}_1 \underline{\phi}_1^H \underline{\omega}_1}{\underline{\omega}_1^H \underline{\Sigma} \underline{\omega}_1} \equiv \underline{\phi}_1 \underline{\phi}_1^H \underline{\omega}_1 = \lambda' \underline{\Sigma} \underline{\omega}_1$$

**We found that:**  $\hat{x}_1 = \underline{\omega}_1^H \underline{y} = \lambda^* \underline{\phi}_1^H \underline{\Sigma}^{-1} \underline{y} \Rightarrow \underline{\omega}_1 = \lambda \underline{\Sigma}^{-1} \underline{\phi}_1$

**Thus:**  $\cancel{\lambda} \underline{\phi}_1 (\underline{\phi}_1^H \underline{\Sigma}^{-1} \underline{\phi}_1) = \lambda' \cancel{\underline{\Sigma} \underline{\Sigma}^{-1}} \underline{\phi}_1 \cancel{\lambda} \Rightarrow \lambda' = (\underline{\phi}_1^H \underline{\Sigma}^{-1} \underline{\phi}_1)!!$

**And we also see that:**  $\max \lambda' = (\underline{\phi}_1^H \underline{\Sigma}^{-1} \underline{\phi}_1) \propto SINR!!$